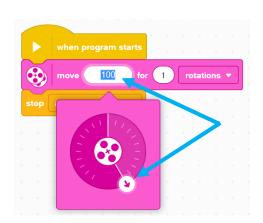


Turning Exercise - Part 1

1. To make your robot **turn sharply**, have the steering on the <Move> Block set to 100. Set the wheel rotations to 1.





2. The wheels make 1 rotation. How far does the robot turn?



Hint: Place your robot on the center of intersecting lines. Line up your wheel axle with one of the lines.

The wheels rotate



The robot turns





3. The wheels make **2 rotations**. Estimate (guess) how far the robot will **turn**.

Now program the robot with 2 wheel rotations. How far does the robot **turn**?



4. The wheels make 4 rotations. Estimate again: how far will the robot turn?

Now program the robot with 4 wheel ro

Now program the robot with 4 wheel rotations. How far does the robot **turn**?

when program starts

move right: 100 for 4 rotations

stop and exit program

move (right: 100) fo

5. Challenge:

The wheels make **1.5 rotations**. Do you know how far the

robot will turn? Write down what you think.

Now program the robot with

1.5 wheel rotations. How far does the robot turn?
